



Image sensors	Sony Pregius IMX296	
Sensor format	1/2.9"	
Chroma	Color and monochrome	
Field of View	62.2° × 48.8° (74.0° diagonally)	
Focal length	4.18 mm	
Aperture	3.0	
Pattern projector	Random dot laser (class 1)	
Projector wavelength	830 nm	
Inertial sensor (IMU)	BNO085	
Max. IMU measurement rate	400 Hz	
Power supply	11.2 - 30 V DC	
Power consumption	9 W	
Dimensions	130 × 92.5 × 34 mm	
Weight (total)	ca. 450 g	
Operation temperature	0 - 40 °C	
I/O	Gigabit Ethernet, GPIO	
Conformity	CE, UKCA, FCC, RoHS, Laser class 1	

Stereo matching

Stereo algorithm	Variation of Semi-Global Matching	
Max. resolution	1440 x 1056 pixels	
Supported pixel formats	Mono8, Mono12, RGB8	
Disparity range	Up to 256 pixels	
Frame rate	Up to 60 fps	
Sub-pixel resolution	4 bits (1/16 pixel)	
Post-processing	Consistency check, uniqueness check, gap interpolation, noise reduction, speckle filtering	
Latency (incl. image capture)	The latency time depends on the chosen configuration. Typical: time between two frames + approx. 9 ms	

Achievable frame rates and image resolutions (recommendations)

Image resolution	Disparity range	Frame rate
1440 x 1056 pixels	256 Pixels	8 fps
720 x 512 pixels	128 pixels	60 fps

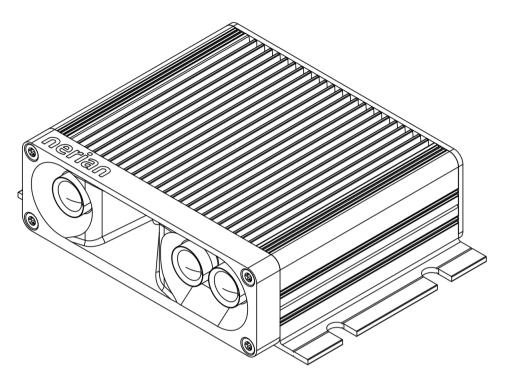


Operation, software, etc.

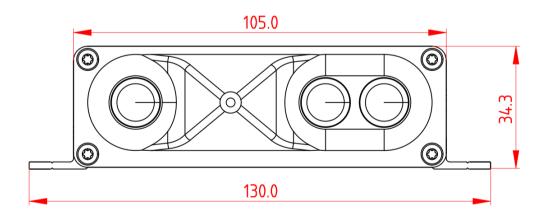
Compatibility	Windows, Linux x86 and ARM OpenCV, Open3D, PCL, Matrox MIL, Halcon, EVT, GenICam
API and software	 C++ and Python API Client software: NVCom GenlCam GenTL Producer ROS Node
Package includes	 3D depth camera 12 V DC power supply with interchangeable mains connectors for Europe, North America, UK and Australia User manual Calibration board
Services	2 year warranty1 year product supportSupport forum



Technical Drawings and Dimensions in mm 3D View

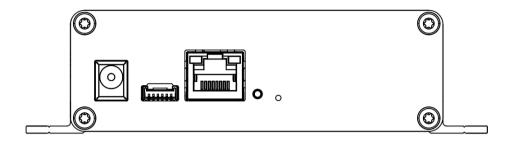


Front





Back



Bottom

