



❖ **CV-L108 CL**
3 CCD RGB Line Scan Camera



adept
electronic solutions

The Machine Vision and
Imaging Specialists

Perth: +61 (08) 9242 5411
Sydney: +61 (02) 9979 2599
Melbourne: +61 (03) 9555 5621
Email: adept@adept.net.au
Web: <http://www.adept.net.au>



- 3 CCD line scan camera with Camera Link output
- Dichroic RGB beam splitter prism with 3 sensors
- 3 sensors with 512 pixels, 14 μm x 14 μm
- 7.168 mm scanning width
- Video output in Camera Link: 24 bit in base configuration. 30 bit in medium
- Scan rate up to 70922 lines per second at 40 MHz pixel clock
- Edge pre-select and pulse width trigger modes
- One-push auto white balance
- Two point flat-field and shading correction
- Knee and binning functions for extended dynamic
- Built-in diagnostics
- Lens adapter for Nikon F-mount or P-mount (M42x1)
- Short ASCII commands set-up via RS 232C or Camera Link
- Setup by Windows NT/2000/XP software



Specifications for CV-L108 CL

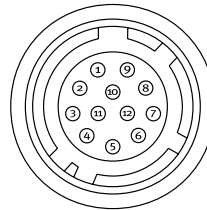
Specifications	CV-L108 CL
Scanning system	Line sensor with internal clock
Pixel clock	40.00 MHz
Sensor	3 line sensors mounted on RGB beam splitter prism
Sensor scanning width	7.168 mm
Cell size	14 (h) x 14 (v) μm
Active pixels	3 x 512 (h) 3 x 256 (h) with 2:1 binning
Sensitivity	Radiometric 7.5 mV/n/cm ² (Gain 0 dB, 600 μs exp., 100% video on G)
Sensitivity	Photometric 162 Lux (4000 K)
S/N ratio	58 dB on green with gain = -3 dB
Video output	24 bit in CL base configuration 30 bit in CL medium configuration
Gain	Master (G). -3 dB to +12 dB R and B. -6 dB to +6 dB
White balance	Manual, fixed or one-push Adjustable range 2800 K to 9000 K Fixed: 4000 K, 4600 K or 5600 K
Knee function	Individual RGB knee point and slope
Shading correction	Individual RGB flat or RB to G (One-push. Range -20%)
Flat-field correction	Two point pixel-to-pixel correction
Synchronization	Internal X-tal or external trigger
Trigger modes	No-shutter, shutter-select and pulse width control
Scan rate	Standard 14.1 μs (no shutter/internal trigger) Programmable 14.1 μs ~14.938ms (1024L), 25ns (internal trigger)
Programmable exposure	50 nsec. to 14.483 msec. in 25 ns increments
Functions controlled by RS 232C or CL	Trigger modes, scan rate, exposure time, gain/black level, shading correction, flat-field correction, white balance, knee-function, diagnostics
Diagnostics	Test pattern. (Color bar, gray pattern and white) LED for power
Lens mount	Nikon F-mount. (Standard) P-mount (M42x1) (Factory option)
Sensor alignment	Better than ± 0.1 pixel
Operating temperature	-5°C to +45°C
Humidity	20 – 80% non-condensing
Storage temp./humidity	-25°C to +60°C/20 – 80% non-condensing
Vibration	3G (20Hz to 200Hz, XYZ direction)
Shock	50G
Regulations	CE (EN61000-6-2 and EN61000-6-3) IEC61000-4-2 Conforming level 4 FCC Part15 Class B RoHS
Power	12V DC \pm 10%. 15W
Dimensions (H x W x D)	90 mm x 90 mm x 90 mm
Weight	830 g

Ordering Information

CV-L108 CL 3 CCD RGB Line Scan Camera. F-mount.
CV-L108 CL 3 CCD RGB Line Scan Camera. P-mount (M42 x 1 thread).

Connection Pin-out

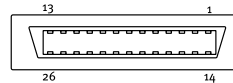
DC In / Trigger



HIROSE HR10A-10R-12PB-01

Pin	Signal
1	Ground
2	+12V DC
3	Ground
4	Reserved
5	Ground
6	RXD RS 232C*
7	TXD RS 232C*
8	Ground
9	XEEN output
10	Trigger input (TTL)*
11	+12V DC
12	Ground

Camera Link Interface

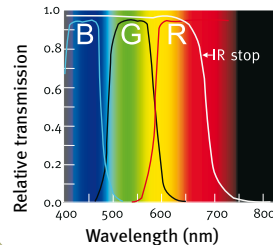


Pin	Signal	Function
1	14	GND
2	15	Xo-/Xo+
3	16	X1-/X1+
4	17	X2-/X2+
5	18	Xclk-/Xclk+
6	19	X3-/X3+
7	20	SerTC+/SerTC- Serial in *
8	21	SerTFG-/SerTFG+ Serial out *
9	22	CC1-/CC1+ Trigger *
10	23	CC2-/CC2+ Reserved
11	24	CC3-/CC3+ Not used
12	25	CC4-/CC4+ Not used
13	26	GND

* In Camera Link or 12 pin Hirose

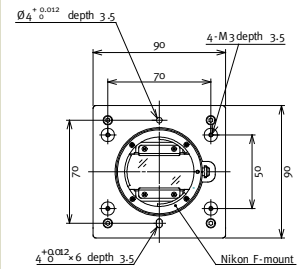
Note:
Camera Link base configuration shown.
For medium configuration refer to Camera Link specifications or operation manual.

Spectral Response

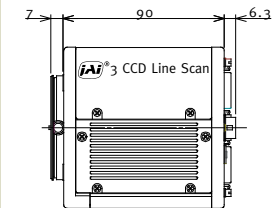


Dimensions

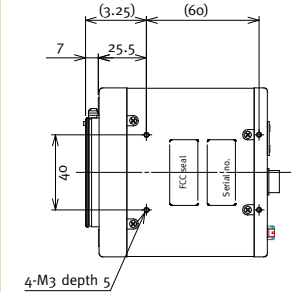
Front view



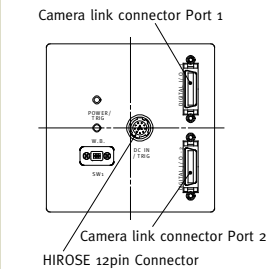
Side view



Bottom view



Rear view



Europe, Middle East & Africa
Phone +45 4457 8888
Fax +45 4491 3252

Asia Pacific
Phone +81 45 440 0154
Fax +81 45 440 0166

Americas
Phone (Toll-Free) 1 800 445 5444
Phone +1 408 383 0300